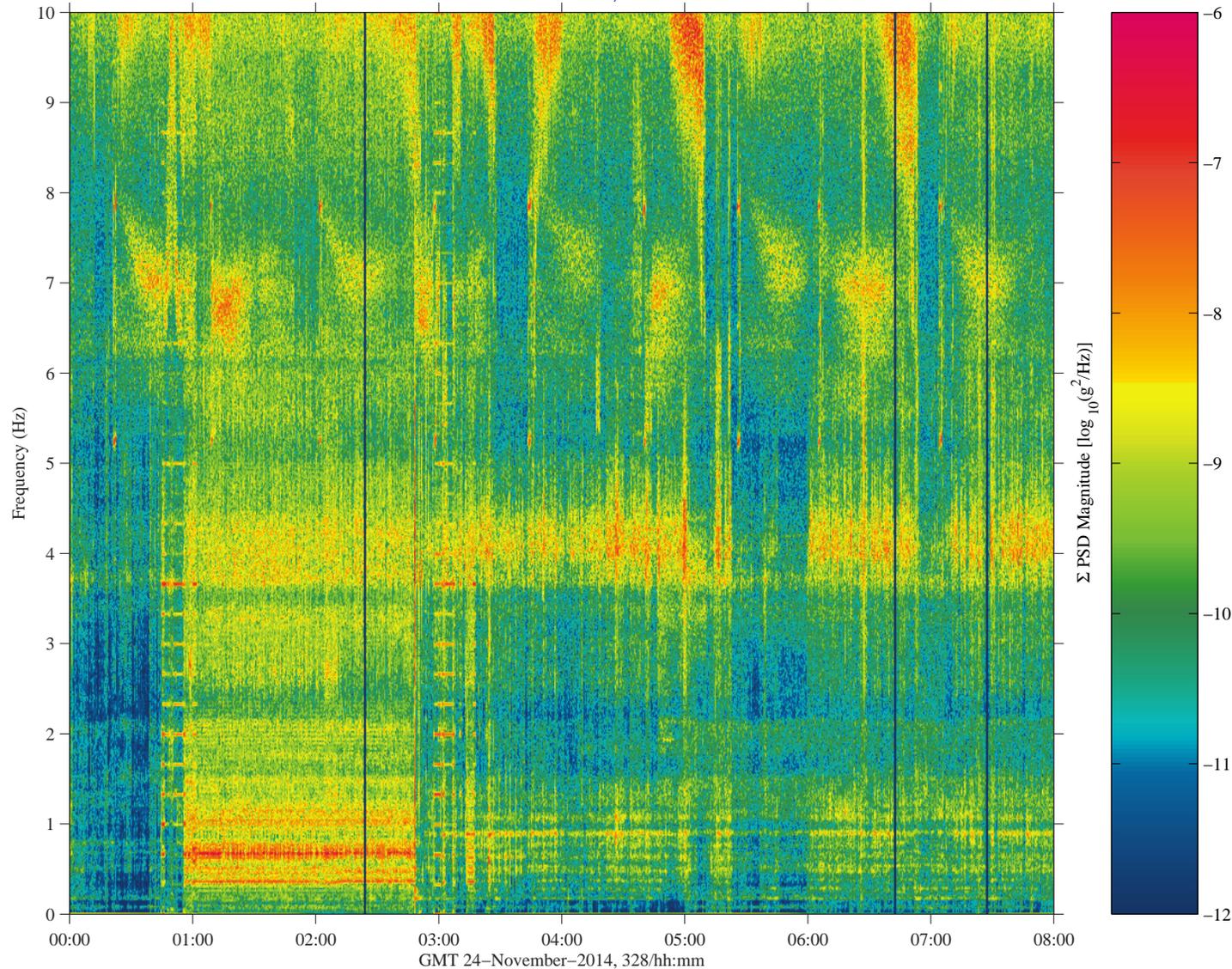


Soyuz 41S Docking Quality

mams, hirap at LAB1O2, ER1, Lockers 3,4:[138.68 -16.18 142.35]
 1000.0000 sa/sec (100.00 Hz)
 $\Delta f = 0.015$ Hz, Nfft = 65536
 Temp. Res. = 32.768 sec, No = 32768

mams, hirap

Start GMT 24–November–2014, 328/00:00:00.001



Description

Sensor	MAMS hirap 1000.0 sa/sec, 100 Hz
Location	LAB1O2, ER1, Lockers 3,4
Plot Type	Spectrogram (< 10 Hz)

Notes:

- This roadmap spectrogram shows an overview of: (1) handover to Russian segment for attitude control at 00:40, (2) maneuver to docking attitude from 00:45 to 01:05, (3) free drift from 02:48 to 02:58 for docking at 02:53, and (4) maneuver to post-docking attitude from 02:58 to 03:21, and (5) handover from Russian segment back to US momentum management at 03:42.
- The most prominent feature seen in the acceleration spectrum is the excitation of structural modes below about 3 Hz during the span when the Russian segment is used for attitude control. This span is seen as the bright red horizontal streaks between about 01:00 and about 03:00 below 3 Hz.

Regime:	Quasi-Steady
Category:	Vehicle
Source:	Soyuz 41S Docking



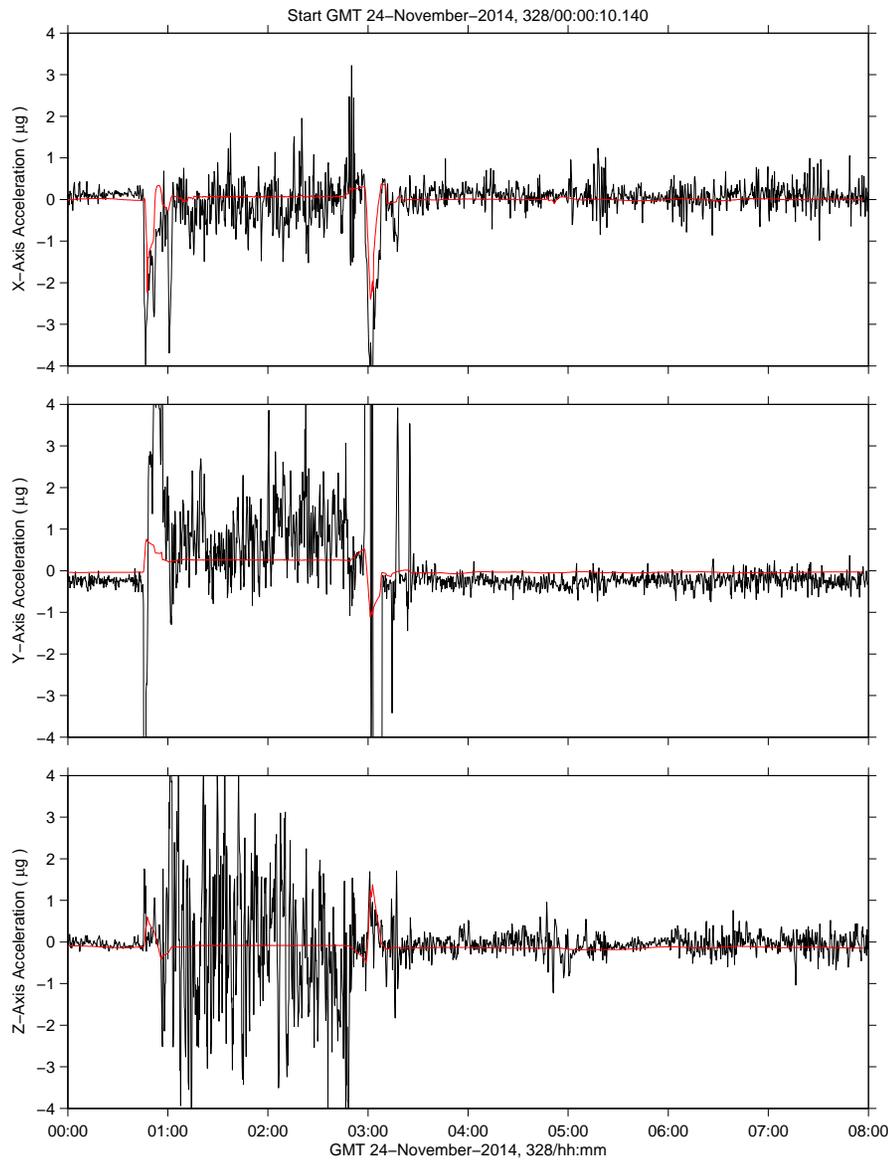
Soyuz 41S Docking Quality

mams_ossbtfm at LAB1O2, ER1, Lockers 3,4 [135.28 -10.68 132.12]
0.0625 sa/sec (0.01 Hz)

Quasi-steady Roadmap
RED LINE IS RADGSE

SSAnalysis[0.0 0.0 0.0]

DELTA S (ossbtfm - radgse): X = -0.0459, Y = 0.0774, Z = 0.0632 (μ g)



Description

Sensor	MAMS ossbtfm 0.0625 sa/sec, 0.01 Hz
Location	LAB1O2, ER1, Lockers 3,4
Plot Type	Acceleration vs. Time

Notes:

- This plot shows the quasi-steady impact of the maneuver to docking attitude between about 00:45 and 01:05 and the maneuver to post-docking LVLH attitude between about 02:58 and 03:21.

Regime:	Quasi-Steady
Category:	Vehicle
Source:	Soyuz 41S Docking



Soyuz 41S Docking Quantify

Vector Magnitude

Description	
Sensor	SAMS 121f03006 142.00 sa/sec, 6.00 Hz
Location	LAB1O1, ER2, Lower Z Panel
Plot Type	Acceleration vs. Time

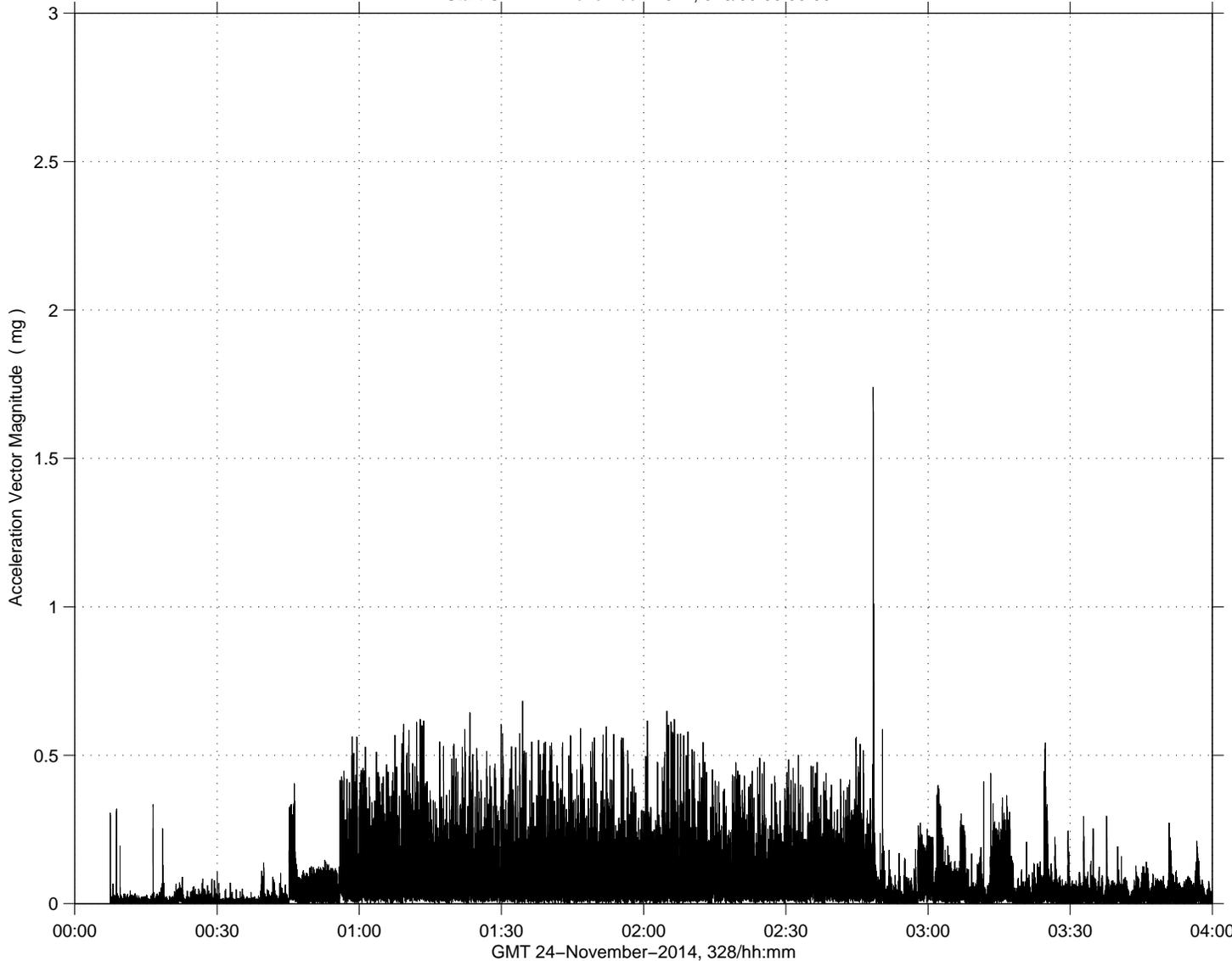
Notes:

- This plot shows the acceleration vector magnitude versus time around the docking of the Soyuz 41S vehicle.
- The measurements shown here came from the SAMS sensor 121f03 in the USL.
- The most prominent feature in these data is the impact of Russian segment attitude control between about 01:00 and 03:00.

Regime:	Quasi-Steady
Category:	Vehicle
Source:	Soyuz 41S Docking

SAMS2, 121f03006, LAB1O1, ER2, Lower Z Panel, 6.0 Hz (142.0 s/sec)

Start GMT 24–November–2014, 328/00:00:00.002



Soyuz 41S Docking Quantify

Vector Magnitude

Description	
Sensor	SAMS 121f05006 142.00 sa/sec, 6.00 Hz
Location	JPM1F5, ER4, Drawer 2
Plot Type	Acceleration vs. Time

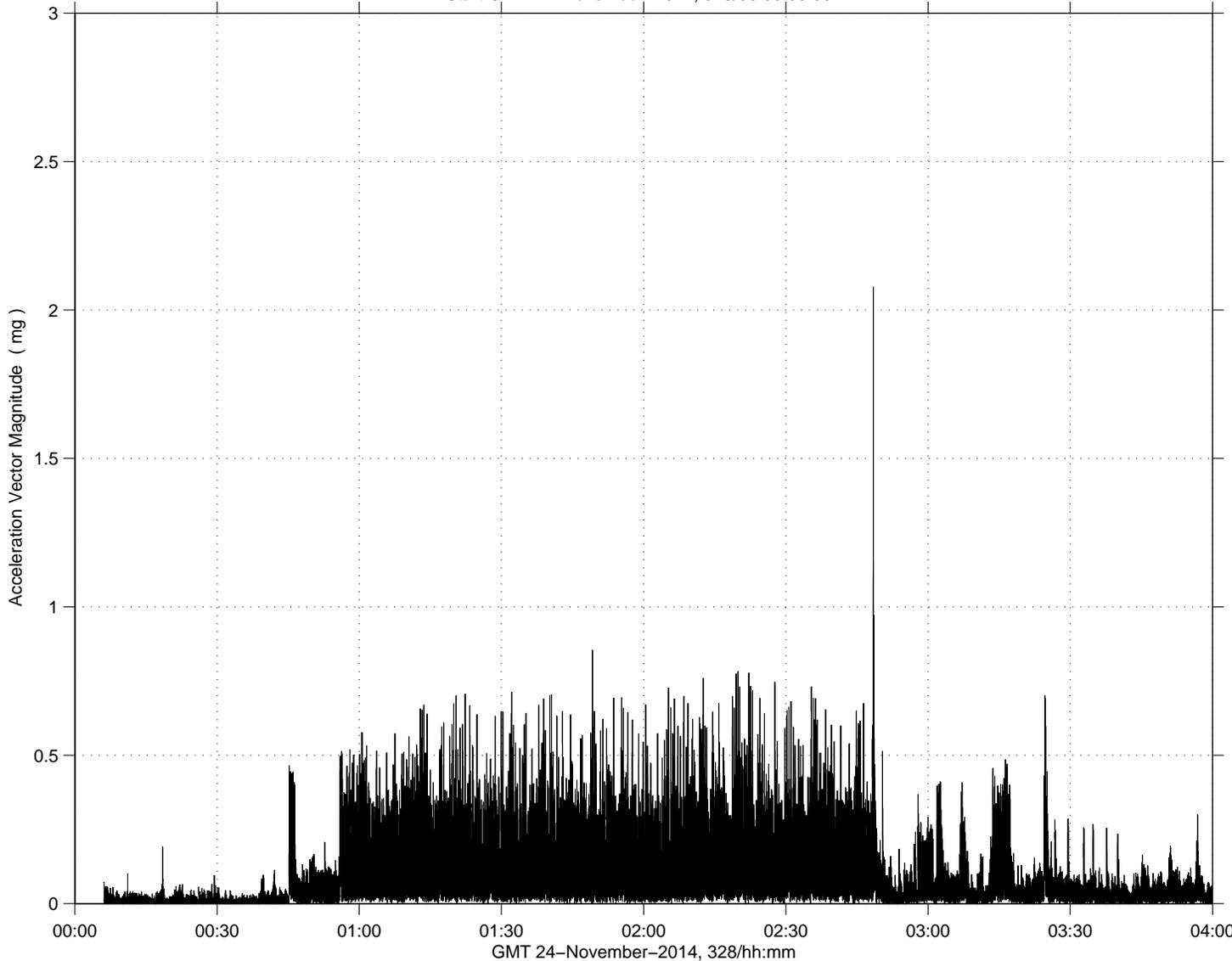
Notes:

- This plot shows the acceleration vector magnitude versus time around the docking of the Soyuz 41S vehicle.
- The measurements shown here came from the SAMS sensor 121f05 in the JEM.
- The most prominent feature in these data is the impact of Russian segment attitude control between about 01:00 and 03:00.

Regime:	Quasi-Steady
Category:	Vehicle
Source:	Soyuz 41S Docking

SAMS2, 121f05006, JPM1F5, ER4, Drawer 2, 6.0 Hz (142.0 s/sec)

Start GMT 24–November–2014, 328/00:00:00.004



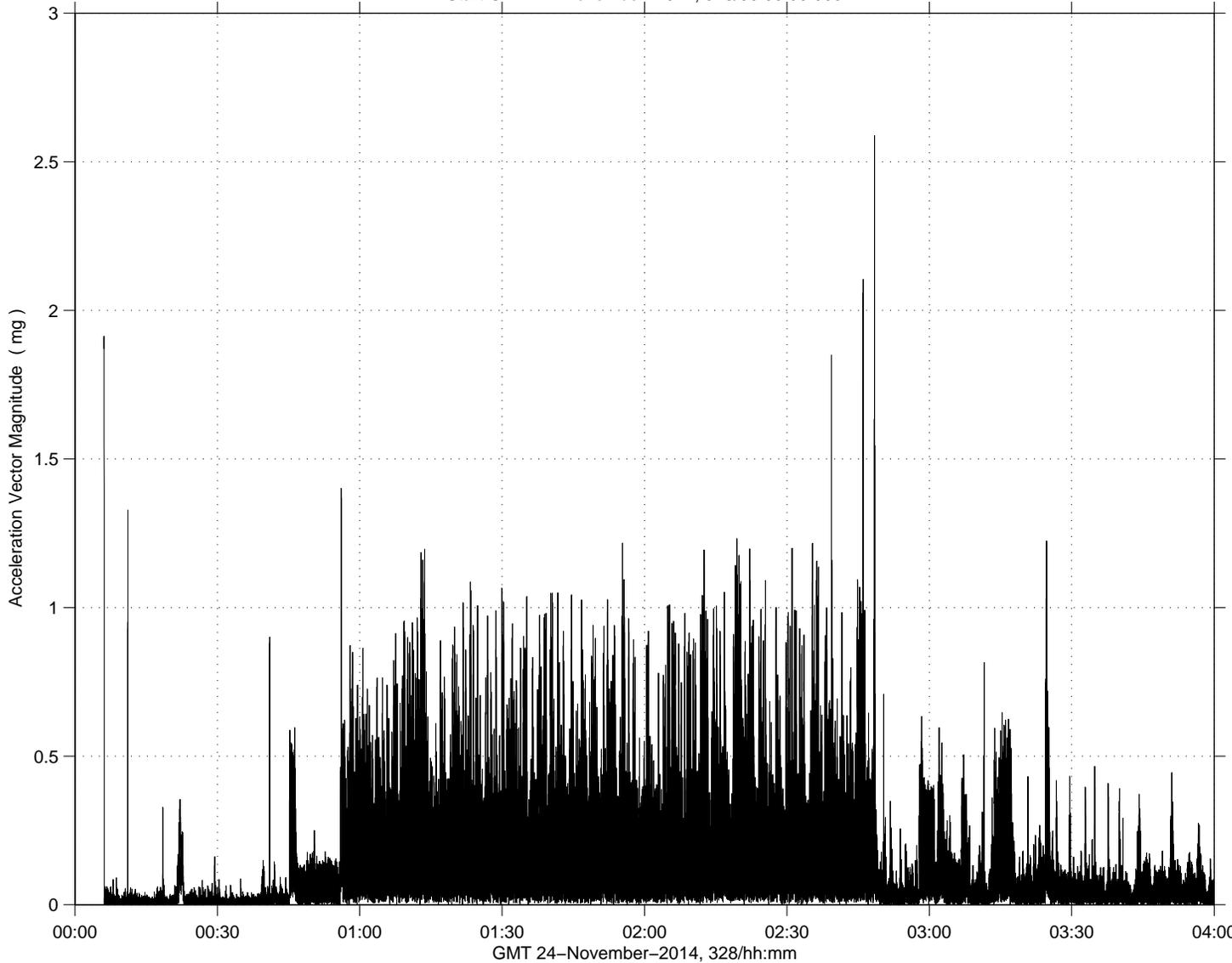
Soyuz 41S Docking Quantify

sams2, 121f08006 at COL1A1, ER3, Seat Track near D1:[371.17 193.43 165.75]
142.0000 sa/sec (6.00 Hz)

SAMS2, 121f08006, COL1A1, ER3, Seat Track near D1, 6.0 Hz (142.0 s/sec)

Vector Magnitude

Start GMT 24–November–2014, 328/00:00:00.003



Description

Sensor	SAMS 121f08006 142.00 sa/sec, 6.00 Hz
Location	COL1A1, ER3, Seat Track near D1
Plot Type	Acceleration vs. Time

Notes:

- This plot shows the acceleration vector magnitude versus time around the docking of the Soyuz 41S vehicle.
- The measurements shown here came from the SAMS sensor 121f08 in the COL.
- The most prominent feature in these data is the impact of Russian segment attitude control between about 01:00 and 03:00.

Regime:	Quasi-Steady
Category:	Vehicle
Source:	Soyuz 41S Docking



Soyuz 41S Docking Ancillary Notes

The previous 3 pages show a quantitative comparison between SAMS sensor measurements in each of the 3 main laboratories: (121f03) in the USL, (121f05) in the JEM, and (121f08) in the COL. It is important to note that these data have been low-pass filtered to highlight the impact of Soyuz docking. The values shown are median acceleration vector magnitudes (after low-pass filtering below 6 Hz) from the time span between GMT 24-Nov-2014/01:00 and 02:30.

SAMS Sensor & Location	Median Accel. Vector Magnitude (ug)
121f03 in USL	99.8
121f05 in JEM	119.1
121f08 in COL	175.6

